

Enigma Level API II

task driven approach

Position Tasks

Creating Positions

`pos = po(7, 3)` "po()" to generate a position
`pos = po({7, 3})` using a table as argument
`pos = obj` every object is a valid position
`pos = po(12.3, 3.7)` a position within a grid (for an actor)

Position Constants

`{7,3}` valid position for all arguments and operations

Coordinate Access

`x,y = pos.x, pos.y` member access
`x,y = pos["x"], pos["y"]` member access
`x,y = pos:xy()`
`x,y = obj.x, obj.y` works on objects too
`x,y = obj:xy()`

Position Calculation

`pos = obj + {2,7}` adding offset
`dpos = obj1 - obj2` difference vector
`dpos2 = 2 * dpos` scalar multiplication
`dpos3 = dpos / 2`
`dpos3 = (obj1 - obj2) / 2` middle between objects

Center positions for set actors

`pos_centered1 = pos + {0.5, 0.5}` by offset
`pos_centered2 = #pos` by special feature
`pos_centered3 = #obj`

Round a position to a grid

`grid_pos = pos:grid()` to integer coordinates
`grid_pos = ((pos1 - pos2)/2):grid()`

Position comparison

`pos_centered1 == pos_centered2` Lua's equality operator
`pos_centered1 ~= pos_centered2` Lua's inequality operator

Position existence

`pos:exists()`

Attribute Tasks

Single Attribute Setting

`obj["destination"] = po(7,3)` simple object attribute
`wo["Brittleness"] = 7.0` global world attribute
`obj["myattribute"] = "what"` userattribute

Multiple Attribute Setting

`obj:set({target=mydoor, action="open"})` set multiple attributes

Requesting Attributes

`value = obj["attr_name"]` get the value
`value = obj.attr_name`
`value = wo["Brittleness"]` get the value of a global level constant
`if wo["IsDifficult"] then ... end` often used difficult-mode switch

Reset Attributes

`obj["length"] = nil` the default length, e.g. '1'
`obj["color"] = nil` delete color attribute - no color
`obj["length"] = DEFAULT` the default length, e.g. '1'

Object Tasks

Creating Objects

`wo[pos] = {"st_chess", color=WHITE, name="Atrax"}` on grid pos
`wo[#pos] = {"ac_bug"}` actor centered on grid pos
`wo[pos] = {"#ac_bug"}` actor centered on grid pos
`wo[pos] = {"ac_bug", 0.3, 0.7}` actor with offsets to pos
`wo[my_floor] = {"it_magicwand"}` set an wand on top of a given floor obj
`wo[pos] = ti["x"]` tile based object definition

Object Naming

`no["Atrax"] = obj`
`wo[pos] = {"st_chess", name="Atrax"}`
`wo[pos] = {"st_chess", "Atrax", color=WHITE }`

Object Autonoming

Each new object will have a unique name.
`wo[pos] = {"st_chess", name="Atrax#"}` autonamed chesstones

Requesting Objects

`obj = no["Atrax"]` named object retrieval from repository
`obj = fl(pos)` floor at pos
`obj = it(x,y)` item at pos
`obj = st(pos)` stone at pos
`obj = wo:it(pos)` item at pos
`my_item = it(my_floor)` get the item that is on top of the given floor

Killing Objects

`wo[pos] = {"it_nil"}`
`obj:kill()` be carefull with kill

Comparing Objects

`obj1 == obj2`
`obj1 ~= obj2`

Existence of an object

`obj:exists()` object exists?
`-obj` unary minus operator on object
`if -obj then ...`

Messages

`my_boulder:message("orientate", WEST)`
`my_boulder:orientate(EAST)`
`my_door:open()`

Object Classification

`obj:is("st_chess")`
`obj:is("st")`
`obj:is("st_chess_black")`

Group Tasks

Creating Groups

```
group = no["Atrax#*"]      a group of all matching objects, wildcards "*" ,"?" allowed
group = grp(obj1, obj2, obj3)  a group of several objects
group = grp({obj1, obj2, obj3}) a group of objects set up in a table
group = grp()                an empty group
```

Group Usage

```
floor_group["friction"] = 3.2  set attribute on all floors in the group
door_group:message("open")     send message to all members
door_group:open()              open all doors in the group
stone_group:kill()
wo[floor_group] = {"it_coin_m"} add some money on all floor positions
wo[pos] = {"st_switch", target=door_group, action="open"} multitargets
wo[pos] = {"st_switch", target="door#*", action="close"}
```

Group Operations

```
doors_lasers = doorgrp + lasergrp  join of two groups
lasergrp      = doors_lasers - doorgrp difference of two groups
common_doors = doorgrp1 * doorgrp2  intersection of two groups
```

Group Members

```
count = #mygroup          - number of objects in the group
obj     = mygroup[5]       - 5th object of the group
obj     = mygroup[-1]      - last object of the group
for i = 1, #mygroup do obj = mygroup[i] ... end
for obj in mygroup do ... end
```

Shuffled Group

```
shuffled_group = sorted_group:shuffle()
shuffled_group = no["Atrax#*"]:shuffle()
```

Sorted Group

```
sorted_group = group:sort("linear", po(2, 1))
sorted_group = group:sort("linear")
sorted_group = group:sort("circular")
sorted_group = group:sort()
```

Subset Group

```
sub_group = group:sub(2)      - first two objects
sub_group = group:sub(-2)     - last two objects
sub_group = group:sub(2, 4)   - objects from 2 to 4
sub_group = group:sub(2, -2)  - two objects starting with 2
```

Nearest Object

```
object = group:nearest(reference)
```

Tiles

Tiles

```
ti["_"] = {"fl_sahara"}      simple tile
ti["_ "] = {"fl_sahara"}    two char tile
ti[".."] = {"fl_sand"}
ti["###"] = {"st_blocker"}
ti["switch_template"] = {"st_switch"}  tiles can hav arbitrary names too
ti[".."] = {"fl_abys"}       redefinition causes error
ti[" w"] = ti[".."] .. {"it_magicwand"} concatenation of several tiles possible
ti[" w"] = {"fl_abys"} .. ti({"it_magicwand"})
```

Named Positions Tasks

Named Position Usage

```
obj["name"] = "anchor1"
obj:kill()
pos = po["anchor1"]      position still available
po["anchor2"] = pos
```

Creating Position Lists

```
polist = po["deepwater#*"]  positionlist with pos
polist = po(grp)            of all group objects
```

Position List Usage

```
wo[polist] = ti["x"]
grp = fl(polist)
```

Position List Operations

```
wo[polist .. po["beach#*"]] = {"it_banana"}
```

Position List Members

```
for i = 1, #pogrp do          iterate over polist
  wo[polist[i]] = {"it_cherry"}
end
```

Other

Nearest Object

```
ti["F"] = {"st_floppy", target="@door#*"}  target is always the nearest door
ti["B"] = {"st_blocker", name="door#"}     resolved at levelloadtime
ti["o"] = {"#ac_pearl_white", "s#", owner=DEFAULT} target is always the currently nearest actor
ti["q"] = {"it_rubberband", anchor2="@s#*"} resolved at runtime when needed
```

Callbacks from switchlike objects

```
function my_callback(value, sender) ... end Sender is the senderobject, value it's state.
```

Checkerboard floor

```
ti["x"] = ti({"fl_rough_red", checkerboard=0}) .. {"fl_rough_blue", checkerboard=1}
```

World

World Initialization

```
width, height = wo(topresolver, defaultkey, map)
width, height = wo(topresolver, defaultkey, width, height)
```

World Advanced Methods

```
wo:add(tile_declarations) wo:add(target, tile_declarations)
wo:drawBorder(upperleft_edge, lowerright_edge, tile)
wo:drawBorder(upperleft_edge, width, height, tile)
wo:drawMap(resolver, anchor, ignore, map, [readdir])
wo:drawMap(resolver, anchor, libmap-map, [readdir])
wo:drawRect(upperleft_edge, lowerright_edge, tile)
wo:drawRect(upperleft_edge, width, height, tile)
wo:shuffle0xyd(rules)
wo:shuffle0xyd() wo:shuffle0xyd({no["borderoxyds#*"]:sort("circular"), circular=true})
wo:shuffle0xyd({"leftoxyds#*", "rightoxyds#*", min=3, max=5})
```

Resolvers

Autotiling

```
res.autotile(subresolver, rules)
res.autotile(ti, {"A", "template_switch"}, {"L", "template_laser"})
res.autotile(ti, {"a", "e", "template_trigger"}, {"A", "E", "template_door"})
```

Composer

```
res.composer(subresolver) res.composer(subresolver, sequence)
res.composer(ti)
res.composer(ti, "211")    decompose the last two chars together
```

Puzzler

load the library before use: `<el:dependency el:path="lib/libpuzzle" el:id="lib/libpuzzle" el:release="3" el:preload="true"/>`

```
res.puzzle(subresolver, rules)
res.puzzle(ti, "B", "Y", "I", "M")    Don't forget appr. tile declarations
```

Random

```
res.random(subresolver, hits, replacements) res.random(ti, "x", {"a", "b"})
res.random(ti, {"x", "y"}, {"i", "j"}, {"a", 2}, {"b", 1})
```

Custom Resolver

```
tile = myresolver(key, x, y)
```